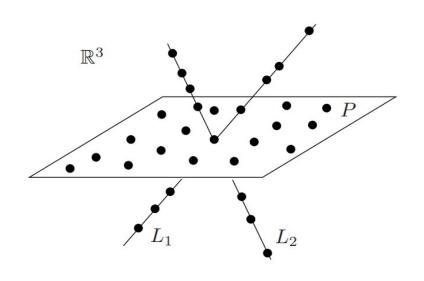
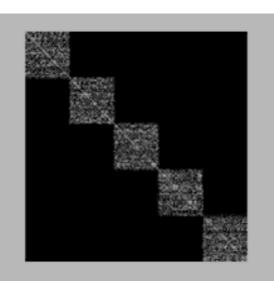
Correlation Adaptive Subspace Segmentation by Trace Lasso Canyi Lu¹, Jiashi Feng¹, Zhouchen Lin², Shuicheng Yan¹ ¹ National University of Singapore, ² Peking University

Subspace Segmentation Problem

Given a set of data vectors $\mathbf{X} = [\mathbf{X}_1, \cdots, \mathbf{X}_k] = [\mathbf{x}_1, \cdots, \mathbf{x}_n] \in \mathbb{R}^{d \times n}$ drawn from a union of k subspaces $\{S_i\}_{i=1}^k$. Let \mathbf{X}_i be a collection of n_i data vectors drawn from the subspace S_i , $n = \sum_{i=1}^k n_i$. The task is to segment the data according to the underlying subspaces they are drawn from.





An example of three subspaces.

Block diagonal affinity matrix.

Related Works

- Spectral Clustering (SC) is used as the framework for subspace segmentation.
- The main challenge by using SC is to define a "good" affinity matrix (or graph) $\mathbf{Z} \in \mathbb{R}^{n \times n}$. Each entry z_{ij} measures the similarity between \mathbf{x}_i and \mathbf{x}_j .
- Ideally, the affinity matrix should be block diagonal (sparsity betweencluster), and has grouping effect (sufficient connections within-cluster).

SSC (Sparse Subspace Clustering) (Elhamifar, CVPR 2009, TPAMI 2013) or *ℓ*₁-Graph (S. Yan, SDM 2009, TIP 2010) :

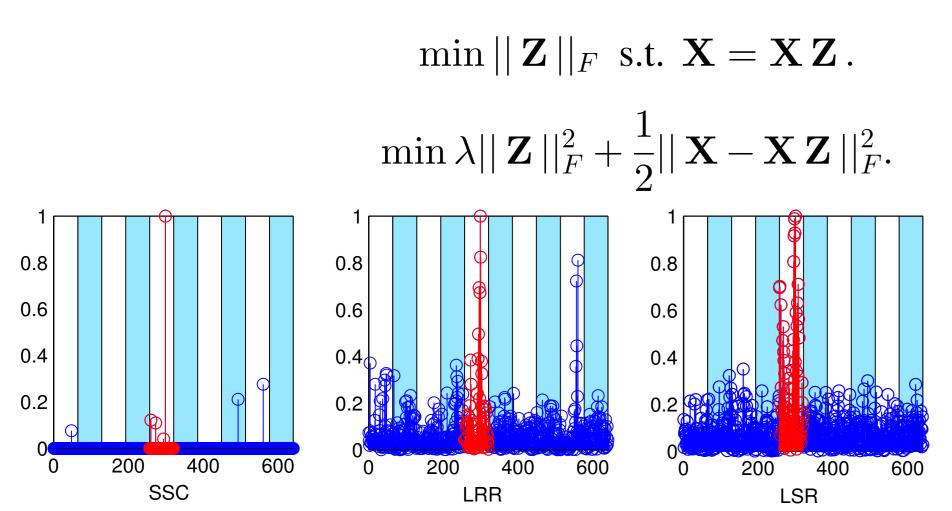
$$\min ||\mathbf{Z}||_1$$
 s.t. $\mathbf{X} = \mathbf{X} \mathbf{Z}$, $\operatorname{diag}(\mathbf{Z}) = \mathbf{Q}$

 $\min \lambda ||\mathbf{Z}||_1 + \frac{1}{2} ||\mathbf{X} - \mathbf{X}\mathbf{Z}||_F^2, \text{ s.t. } \operatorname{diag}(\mathbf{Z}) = 0.$ LRR (Low-Rank Representation) (G. Liu et al., ICML 2010, TPAMI 2012):

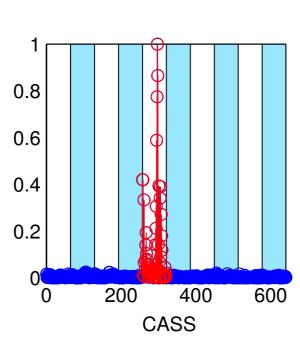
$$\min ||\mathbf{Z}||_* \text{ s.t. } \mathbf{X} = \mathbf{X} \mathbf{Z}.$$

 $\min \lambda || \mathbf{Z} ||_* + || \mathbf{X} - \mathbf{X} \mathbf{Z} ||_{2,1}.$

LSR (Least Squares Regression) (C. Lu and S. Yan, ECCV 2012):



SSC pursues sparsity, but has no grouping effect. LRR and LSR have strong grouping effect, but weak in sample selection. A better choice, balances SSC (ℓ_1) and LSR (ℓ_2).



Correlation Adaptive Subspace Segmentation

Trace Lasso is an adaptive norm which balances the ℓ_1 -norm and ℓ_2 -norm. It is formally defined as

 $\Omega(\mathbf{w}) = ||\mathbf{X}\operatorname{Diag}(\mathbf{w})||_{*}.$ If the data are uncorrelated (the data points are orthogonal, $\mathbf{X}^T \mathbf{X} = \mathbf{I}$), trace

Lasso is equal to the ℓ_1 -norm:

 $|| \mathbf{X} \operatorname{Diag}(\mathbf{w}) ||_{*} = || \operatorname{Diag}(\mathbf{w}) ||_{*} =$

If the data are highly correlated (the data points are all the same, $\mathbf{X} = \mathbf{x}_1 \mathbf{1}^T$, $\mathbf{X}^T \mathbf{X} = \mathbf{1}\mathbf{1}^T$), trace Lasso is equal to the ℓ_2 -norm:

 $||\mathbf{X} \operatorname{Diag}(\mathbf{w})||_{*} = ||\mathbf{x}_{1}\mathbf{w}^{T}||_{*} = ||\mathbf{x}_{1}||_{2}||\mathbf{w}||_{2} = ||\mathbf{w}||_{2}.$

For other cases, trace Lasso interpolates between the ℓ_2 -norm and ℓ_1 -norm:

 $||\mathbf{w}||_2 \le ||\mathbf{X} \operatorname{Diag}(\mathbf{w})||_* \le ||\mathbf{w}||_1.$

Generally speaking, trace Lasso is adaptive to the correlation of X. If X is of low correlation, trace Lasso is close to the ℓ_1 -norm. If X is of high correlation, trace Lasso is close to the ℓ_2 -norm.

Correlation Adaptive Subspace Segmentation (CASS) CASS with clean data:

> $\min_{\mathbf{w} \in \mathbb{R}^n} || \mathbf{X} \operatorname{Diag}(\mathbf{w}) ||_* \text{ s.t. } \mathbf{y} = \mathbf{X} \mathbf{w}.$ (1)

Enforced Block Sparse (EBS) Conditions. Given a matrix $\mathbf{X} \in \mathbb{R}^{d \times n}$ and a vector $\mathbf{w} = [\mathbf{w}_a; \mathbf{w}_b; \mathbf{w}_c] \in \mathbb{R}^n$, $\mathbf{w} \neq \mathbf{0}$. Let $\mathbf{w}^B = [\mathbf{0}; \mathbf{w}_b; \mathbf{0}] \in \mathbb{R}^n$. Saying $f(\mathbf{X}, \mathbf{w})$ satisfies the EBS conditions if

(1) $f(\mathbf{X}, \mathbf{w}) = f(\mathbf{X} \mathbf{P}, \mathbf{P}^{-1} \mathbf{w})$, for any permutation matrix $\mathbf{P} \in \mathbb{R}^{n \times n}$; (2) $f(\mathbf{X}, \mathbf{w}) \ge f(\mathbf{X}, \mathbf{w}^B)$, and the equality holds if and only if $\mathbf{w} = \mathbf{w}^B$.

Theorem 1 If $f(\mathbf{X}, \mathbf{w})$ satisfies the EBS conditions, and the data in $\mathbf{X} =$ $[\mathbf{X}_1, \cdots, \mathbf{X}_k]$ are drawn from independent subspaces. y is a new point in \mathcal{S}_i . The solution to the following problem

 $\min_{\mathbf{w}} f(\mathbf{X}, \mathbf{w}) \quad s.t. \quad \mathbf{y} =$

is block sparse, i.e., $\mathbf{w}_i^* \neq 0$ and $\mathbf{w}_i^* = 0$, for all $j \neq i$.

Theorem 2 Trace Lasso $|| \mathbf{X} Diag(\mathbf{w}) ||_*$ satisfies the EBS conditions. Thus the solution to problem (1) is block sparse when the subspaces are independent.

The block sparse property guarantees that CASS achieves perfect segmentation under certain condition as other methods, e.g. LRR and LSR. CASS with noisy data:

$$\min_{\mathbf{w}} \lambda || \mathbf{X} \operatorname{Diag}(\mathbf{w}) ||_{*} + \frac{1}{2} || \mathbf{y} - \mathbf{X} \mathbf{w} ||_{2}^{2}.$$
(2)

$$\sum_{i=1}^{n} |w_i| = ||\mathbf{w}||_1$$

$$= \mathbf{X} \mathbf{w},$$

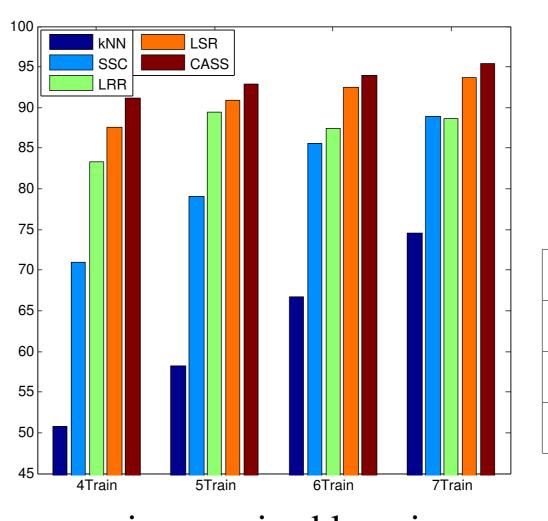
Theorem 3 (*The Grouping Effect*). Given a data vector $\mathbf{y} \in \mathbb{R}^d$, data points $\mathbf{X} = [\mathbf{x}_1, \cdots, \mathbf{x}_n] \in \mathbb{R}^{d \times n}$ and parameter $\lambda > 0$. Let $\mathbf{w}^* = [w_1^*, \cdots, w_n^*]^T \in \mathbb{R}^{d \times n}$ \mathbb{R}^n be the optimal solution to problem (2). If $\mathbf{x}_i \to \mathbf{x}_j$, then $w_i^* \to w_j^*$.

The grouping effect of CASS guarantees that if x_i and x_j are highly correlated, their corresponding coefficients are almost the same. Then they tends to be grouped together.

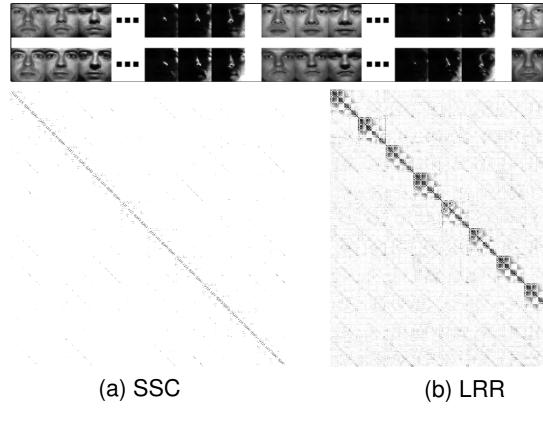
Segmentation Algorithm.

- $[\mathbf{w}_1^*,\cdots,\mathbf{w}_n^*].$
- 2. Construct the affinity matrix by $(|\mathbf{W}^*| + |\mathbf{W}^{*T}|)/2$.
- 3. Segment the data into k groups by Normalized Cuts.

Experiments







Take Home Message

- method by using the trace Lasso.



1. For each \mathbf{x}_i in \mathbf{X} , solve problem (2) based on the dictionary $\mathbf{X}_{\hat{i}}$ = $[\mathbf{x}_1, \cdots, \mathbf{x}_{i-1}, \mathbf{x}_{i+1}, \cdots, \mathbf{x}_n]$. Denote the coefficient as \mathbf{w}_i^* . Let $\mathbf{W}^* =$

Segmentation errors (%) on the Hopkins 155 data.						
		kNN	SSC	LRR	LSR	CASS
MAX		45.59	39.53	36.36	36.36	32.85
ME	AN	13.44	4.02	3.23	2.50	2.42
STD)	12.90	10.04	6.60	5.62	5.84
Face clustering accuracy on the Yalbe B database.						
		kNN	SSC	LRR	LSR	CASS
5 subjects		56.88	80.31	86.56	92.19	94.03
8 subjects		52.34	62.90	78.91	80.66	91.41
10 subjects		50.94	52.19	65.00	73.59	81.88
Digit clustering accuracy on the MNIST database.						
		kNN	SSC	LRR	LSR	CASS
AC	CC.	61.00	62.60	66.80	68.00	73.80
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ernakatusi di S	(c) LSR			(d) CASS		

Affinity matrices obtained by different methods on the Yale B database.

• We propose the Correlation Adaptive Subspace Segmentation (CASS)

• CASS is adaptive to the data correlation. When the data correlation is low, it is close to SSC. When the data correlation is high, it is close to LSR. • CASS leads to a block diagonal representation and has the grouping effect.